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HYCON2 Show Day Traffic Modeling, Estimation and Control

- May 13th, 2014 -









Traffic Modeling, Estimation and Control

HYCON 2 (Highly-complex and networked control systems) is a EU FP7 Network of Excellence. It aims at stimulating and establishing the long-term integration of the European research community, leading institutions and industry in the strategic field of control of complex, large-scale, and networked dynamical systems. HYCON2 has identified several applications, among which a show-case on "Traffic Modeling, Estimation and Control".

This show-day presents methods and results for the traffic show-case application, which corresponds to the operation of the freeway network around the Grenoble area; the selected road is Grenoble South Ring (Rocade sud).

This research activity has been performed thanks to the use of the Grenoble Traffic Lab (GTL) initiative: a traffic data center (platform) that collects traffic road-infrastructure information in real time. Sensed information comes from a dense wireless sensor network deployed on Grenoble South Ring, providing macroscopic traffic signals such as flows, velocities, etc.

Some specific tasks realized during this project are:

- Building the traffic data center with magnetic data (data collection, web interface);
- Building the show room (display screens, simulators)
- Calibrating a microscopic simulator from macroscopic data;
- Identifying and classifying a set of specific control and estimation problems;
- Devising innovative methods for: modeling, estimation, and control for the show case:
- Evaluating the proposed solutions with real data when possible, and with synthetic data from the microscopic simulator otherwise.

The partners of **HYCON2** actively involved in this activity have been: NeCS INRIA/U. Grenoble/CNRS. Univ. Pavia, Univ. L'Aquila, TU Delft, Univ. Sevilla, Lund Univ. Moreover, a strong collaboration has been developed with Univ. Genova.

PROGRAM

9:00-12:00

Plenary talks

- Presentation of the show-case and of GTL (Grenoble Traffic Lab)
 Carlos Canudas de-Wit
- Methods and results for traffic prediction (model-free methods)
 Luis Leon
- Methods and results for traffic prediction (model-based methods)
 Fabio Morbidi

Coffee break

- Innovative MPC schemes for freeway traffic control Antonella Ferrara, Simona Sacone, and Silvia Siri
- Optimal density-balancing control for freeway traffic Dominik Pisarski

12:00-13:30

16:00-16:30

Lunch

Demonstrations and poster session

Visit of the GTL show-room and demo of GTL functionalities. Participants are divided in small groups for this visit, while, in parallel the poster session takes place.

- Nash Game Based Distributed Control Design for Balancing of Traffic Density over Freeway Networks (+demo) by D. Pisarski and C. Canudas de Wit (NeCS INRIA/U. Grenoble/CNRS)
- Hybrid Model Predictive Control for Freeway Traffic Using Discrete Speed Limit Signals, by J.R.D. Frejo, A. Nuñez, B. De Schutter, and E.F. Camacho (Univ. Sevilla and TU Delft)
- Distributed Model Predictive Control for Freeway Traffic Systems, by J.R.D. Frejo and E.F. Camacho (Univ. Sevilla)
- On Resilience of Multicommodity
 Dynamical Flow Networks, by G.
 Nilsson, G. Como and E. Lovisari
 (Lund Univ.)

- Short-Term Multiple Step Ahead Travel Time Forecasting: Model-free Approach (+demo), by L. Leon Ojeda, A. Kibangou, and C. Canudas de Wit (NeCS INRIA/U. Grenoble/CNRS)
- A New Robust Approach for Highway Traffic Density Estimation, by F. Morbidi, L. Leon Ojeda, C. Canudas de Wit, I. Bellicot (NeCS INRIA/U. Grenoble/CNRS)
- Innovative Model Predictive Control Schemes for Freeway Traffic Control (+demo), by A. Ferrara, A. Nai Oleari, Simona Sacone, and Silvia Siri (Univ. Pavia and Univ. Genova)
- ECO-Driving in Urban Traffic Networks using Traffic Signal Information, by G. De Nunzio, C. Canudas de Wit, and P. Moulin (NeCS INRIA/U. Grenoble/CNRS and IFPEN)

Round-table discussion & conclusion